

A theory of generalized Donaldson–Thomas invariants

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1. Introduction

Let X be a Calabi–Yau 3-fold, and $\mathcal{A} = \text{coh}(X)$ the abelian category of *coherent sheaves* on X . Write $K(\mathcal{A})$ for the *numerical Grothendieck group* of \mathcal{A} . If E is a coherent sheaf on X , write $[E]$ for its class in $K(\mathcal{A})$. The *Chern character* $\text{ch}(E)$ lies in $H^{\text{even}}(X; \mathbb{Q})$. It descends to a group morphism $\text{ch} : K(\mathcal{A}) \rightarrow H^{\text{even}}(X; \mathbb{Q})$. So $K(\mathcal{A})$ is a finite rank lattice \mathbb{Z}^n , a subgroup of $H^{\text{even}}(X; \mathbb{Q})$. The *Euler form* is $\chi : K(\mathcal{A}) \times K(\mathcal{A}) \rightarrow \mathbb{Z}$, antisymmetric and biadditive. Using Serre duality gives

$$\begin{aligned} & \dim \text{Hom}(E, F) - \dim \text{Ext}^1(E, F) \\ & - \dim \text{Hom}(F, E) + \dim \text{Ext}^1(F, E) = \chi([E], [F]). \end{aligned} \tag{1}$$

Choose an ample line bundle \mathcal{L} on X . This induces a notion of *Gieseker stability* on $\mathcal{A} = \text{coh}(X)$. Write τ for the stability condition coming from \mathcal{L} . It depends on \mathcal{L} , so a different ample line bundle $\tilde{\mathcal{L}}$ induces a different stability condition $\tilde{\tau}$.

Given $\alpha \in K(\mathcal{A})$, we can form the moduli spaces $\mathcal{M}_{\text{st}}^\alpha(\tau), \mathcal{M}_{\text{SS}}^\alpha(\tau)$ of τ -(semi)stable sheaves E in \mathcal{A} with $[E] = \alpha$ in $K(\mathcal{A})$. We can regard these as *schemes*, with points of $\mathcal{M}_{\text{SS}}^\alpha(\tau)$ being S-equivalence classes of τ -semistable sheaves, rather than isomorphism classes. Alternatively, we can regard them as *Artin stacks*, as open constructible subsets in the moduli stack \mathfrak{M} of all coherent sheaves.

Donaldson–Thomas invariants $DT^\alpha(\tau)$ are integer-valued invariants ‘counting’ τ -(semi) stable sheaves in class $\alpha \in K(\mathcal{A})$. They are defined only in the case when $\mathcal{M}_{\text{st}}^\alpha(\tau) = \mathcal{M}_{\text{ss}}^\alpha(\tau)$, that is, when there are no strictly semistable sheaves in class α .

The interesting property of Donaldson–Thomas invariants is that they are unchanged by continuous deformations of the underlying Calabi–Yau 3-fold X , that is, they are independent of the complex structure J of X up to deformation. This is a strong statement, as deforming X can change \mathcal{A} and $\mathcal{M}_{\text{st}}^\alpha(\tau)$ radically.

Until now, it was not known how $DT^\alpha(\tau)$ depends on τ , that is, on the choice of ample line bundle L .

Kai Behrend showed that $\mathrm{DT}^\alpha(\tau)$ can be written as a *weighted Euler characteristic*

$$\mathrm{DT}^\alpha(\tau) = \int_{\mathcal{M}_{\mathrm{st}}^\alpha(\tau)} \nu \, d\chi, \quad (2)$$

where ν is the ‘microlocal function’, a \mathbb{Z} -valued constructible function on $\mathcal{M}_{\mathrm{st}}^\alpha(\tau)$ depending only on the scheme structure of $\mathcal{M}_{\mathrm{st}}^\alpha(\tau)$. We think of ν as a *multiplicity function*. If $\mathcal{M}_{\mathrm{st}}^\alpha(\tau)$ is a k -fold point $\mathrm{Spec} \mathbb{C}[z]/(z^k)$ then $\nu \equiv k$. If $\mathcal{M}_{\mathrm{st}}^\alpha(\tau)$ is smooth of dimension d then $\nu \equiv (-1)^d$.

In a series of previous papers, I defined a different set of invariants $J^\alpha(\tau) \in \mathbb{Q}$ ‘counting’ τ -semistable sheaves in class α . They are defined for all $\alpha \in K(\mathcal{A})$, including classes with strictly semistables. If $\mathcal{M}_{\text{st}}^\alpha(\tau) = \mathcal{M}_{\text{ss}}^\alpha(\tau)$ then $J^\alpha(\tau)$ is the (unweighted) Euler characteristic $\chi(\mathcal{M}_{\text{st}}^\alpha(\tau)) \in \mathbb{Z}$.

The important property of the $J^\alpha(\tau)$ is that their transformation law under change of stability condition is known: we can write $J^\alpha(\tilde{\tau})$ as a sum of products of $J^\beta(\tau)$, with combinatorial coefficients.

However, the $J^\alpha(\tau)$ are not invariant under deformations of the underlying Calabi-Yau 3-fold. This is because they do not count points in $\mathcal{M}_{\text{st}}^\alpha(\tau)$ with multiplicity, so a k -fold point $\text{Spec } \mathbb{C}[z]/(z^k)$ in $\mathcal{M}_{\text{st}}^\alpha(\tau)$ would contribute 1 to $J^\alpha(\tau)$, for instance.

The goal of the project

We will define a family of *generalized D–T invariants* $\bar{DT}^\alpha(\tau) \in \mathbb{Q}$ defined for all $\alpha \in K(\mathcal{A})$, combining the good properties of both the D–T invariants $DT^\alpha(\tau)$, and my invariants $J^\alpha(\tau)$. That is:

- $\bar{DT}^\alpha(\tau)$ is unchanged by deformations of the underlying Calabi–Yau 3-fold.
- If $\mathcal{M}_{\text{st}}^\alpha(\tau) = \mathcal{M}_{\text{ss}}^\alpha(\tau)$ then $\bar{DT}^\alpha(\tau) = DT^\alpha(\tau)$.
- The $\bar{DT}^\alpha(\tau)$ transform according to a known transformation law under change of stability condition. (As for the $J^\alpha(\tau)$, but with sign changes).

The general method is fairly obvious: we define $\bar{DT}^\alpha(\tau)$ by inserting Behrend’s microlocal function ν as a weight in the definition of my $J^\alpha(\tau)$, so that the $\bar{DT}^\alpha(\tau)$ count sheaves with the correct multiplicity. But the details are complex.

2. A sketch of the $J^\alpha(\tau)$ set up

The invariants $J^\alpha(\tau)$, and other invariants, are defined and studied in 7 papers (the main four on ‘Configurations in abelian categories’) totalling 412 journal pages. Here is an oversimplified sketch:

Write $\mathcal{M}_{\mathcal{A}}$ for the moduli stack of sheaves in \mathcal{A} , an Artin stack. We define a \mathbb{Q} -vector space of ‘stack functions’ $SF(\mathcal{M}_{\mathcal{A}})$, a generalization of \mathbb{Q} -valued constructible functions on $\mathcal{M}_{\mathcal{A}}$. Loosely, $SF(\mathcal{M}_{\mathcal{A}})$ is the Grothendieck ring of the (2-)category of Artin stacks over $\mathcal{M}_{\mathcal{A}}$, tensored with \mathbb{Q} . Then $SF(\mathcal{M}_{\mathcal{A}})$ has an associative, non-commutative product $*$ making it into a \mathbb{Q} -algebra, a kind of universal Ringel–Hall algebra. For $f, g \in SF(\mathcal{M}_{\mathcal{A}})$, think of $(f * g)(F)$ as the ‘integral’ of $f(E)g(G)$ over all exact sequences $0 \rightarrow E \rightarrow F \rightarrow G \rightarrow 0$ in \mathcal{A} .

This $*$ induces a Lie bracket $[\cdot, \cdot]$ on $\text{SF}(\mathcal{M}_{\mathcal{A}})$ by $[f, g] = f * g - g * f$. There is a vector subspace $\text{SF}^{\text{ind}}(\mathcal{M}_{\mathcal{A}})$ of $\text{SF}(\mathcal{M}_{\mathcal{A}})$, the stack functions ‘supported on (virtual) indecomposables’, which is closed under $[\cdot, \cdot]$ (though not under $*$). Thus $\text{SF}^{\text{ind}}(\mathcal{M}_{\mathcal{A}})$ is a *Lie subalgebra* of $\text{SF}(\mathcal{M}_{\mathcal{A}})$.

Given a stability condition τ on \mathcal{A} , we define elements $\bar{\delta}_{\text{SS}}^{\alpha}(\tau)$ for $\alpha \in K(\mathcal{A})$ to be the ‘characteristic function’ of $\mathcal{M}_{\text{SS}}^{\alpha}(\tau)$, regarded as a substack of $\mathcal{M}_{\mathcal{A}}$.

We prove a *universal transformation law* for the $\bar{\delta}_{\text{SS}}^{\alpha}(\tau)$ under change of stability condition. That is, given two stability conditions $\tilde{\tau}, \tau$ on \mathcal{A} , we can write $\bar{\delta}_{\text{SS}}^{\alpha}(\tilde{\tau})$ as a sum of products of $\bar{\delta}_{\text{SS}}^{\beta}(\tau)$ using $*$, with combinatorial coefficients in \mathbb{Z} .

If $\mathcal{M}_{\text{st}}^\alpha(\tau) \neq \mathcal{M}_{\text{ss}}^\alpha(\tau)$ then $\bar{\delta}_{\text{ss}}^\alpha(\tau)$ does not lie in the Lie subalgebra $\text{SF}^{\text{ind}}(\mathcal{M}_{\mathcal{A}})$. Using the $\bar{\delta}_{\text{ss}}^\alpha(\tau)$ we define elements $\bar{\epsilon}^\alpha(\tau)$ for $\alpha \in K(\mathcal{A})$ which do lie in $\text{SF}^{\text{ind}}(\mathcal{M}_{\mathcal{A}})$. We have $\bar{\epsilon}^\alpha(\tau) = \bar{\delta}_{\text{ss}}^\alpha(\tau)$ if $\mathcal{M}_{\text{st}}^\alpha(\tau) = \mathcal{M}_{\text{ss}}^\alpha(\tau)$. Think of $\bar{\epsilon}^\alpha(\tau)$ as a weighted version of $\bar{\delta}_{\text{ss}}^\alpha(\tau)$, where stables have weight 1, indecomposable semistables have weights in \mathbb{Q} , and decomposables have weight 0.

The $\bar{\epsilon}^\alpha(\tau)$ also satisfy a *universal transformation law* under change of stability condition, with coefficients in \mathbb{Q} . It can be written solely using the Lie bracket $[\cdot, \cdot]$ on $\text{SF}^{\text{ind}}(\mathcal{M}_{\mathcal{A}})$, rather than $*$ on $\text{SF}(\mathcal{M}_{\mathcal{A}})$.

All the above works for very general abelian categories, e.g. $\mathcal{A} = \text{coh}(P)$ for P a smooth projective variety over \mathbb{K} algebraically closed of characteristic zero.

Now we use the Calabi–Yau 3-fold assumption. Define a Lie algebra $C(\mathcal{A}, \chi)$ to have basis, as a \mathbb{Q} -vector space, symbols c^α for $\alpha \in K(\mathcal{A})$, and Lie bracket

$$[c^\alpha, c^\beta] = \chi(\alpha, \beta) c^{\alpha+\beta}, \quad (4)$$

where χ is the Euler form. As χ is anti-symmetric this satisfies the Jacobi identity. We define a linear map $\Psi : \mathrm{SF}^{\mathrm{ind}}(\mathcal{M}_{\mathcal{A}}) \rightarrow C(\mathcal{A}, \chi)$ by $\Psi(f) = \sum_{\alpha \in K(\mathcal{A})} \bar{\chi}(f|_{\mathcal{M}_{\mathcal{A}}^\alpha}) c^\alpha$, where $\mathcal{M}_{\mathcal{A}}^\alpha$ is the substack of sheaves in class α in $\mathcal{M}_{\mathcal{A}}$, and $\bar{\chi}$ is a kind of stack-theoretic Euler characteristic.

Here $\bar{\chi}$ is not easy to define. The natural Euler characteristic of a quotient stack $[X/G]$ should be $\bar{\chi}([X/G]) = \chi(X)/\chi(G)$, but $\chi(G) = 0$ for any algebraic group of positive rank, so we have to divide by zero.

The point about $SF^{\text{ind}}(\mathcal{M}_{\mathcal{A}})$ is that we can write $f \in SF^{\text{ind}}(\mathcal{M}_{\mathcal{A}})$ using only $[X/G]$ with $\text{rank}(G) = 1$, and then set $\bar{\chi}([X/G]) = \chi(X)/\chi(G/\mathbb{C}^{\times})$, where \mathbb{C}^{\times} is the maximal torus of G , and $\chi(G/\mathbb{C}^{\times}) \neq 0$.

Using the Calabi-Yau 3-fold property, equation (1), we can show that $\Psi : SF^{\text{ind}}(\mathcal{M}_{\mathcal{A}}) \rightarrow C(\mathcal{A}, \chi)$ is a *Lie algebra morphism*.

We then define invariants $J^{\alpha}(\tau) \in \mathbb{Q}$ by $\Psi(\bar{\epsilon}^{\alpha}(\tau)) = J^{\alpha}(\tau)c^{\alpha}$ for all $\alpha \in K(\mathcal{A})$.

Since the $\bar{\epsilon}^{\alpha}(\tau)$ satisfy a universal transformation law in the Lie algebra $SF^{\text{ind}}(\mathcal{M}_{\mathcal{A}})$ under change of stability condition, and Ψ is a Lie algebra morphism, the images $J^{\alpha}(\tau)c^{\alpha}$ satisfy the same transformation law in the Lie algebra $C(\mathcal{A}, \chi)$.

This yields a transformation law for the $J^\alpha(\tau)$ under change of stability condition, of the form

$$\begin{aligned}
 J^\alpha(\tilde{\tau}) = & \sum_{\substack{\text{iso. classes} \\ \text{of } \Gamma, I, \kappa}} \pm U(\Gamma, I, \kappa; \tau, \tilde{\tau}) \cdot \\
 & \prod_{i \in I} J^{\kappa(i)}(\tau) \cdot \\
 & \prod_{\substack{\text{edges} \\ i-j \text{ in } \Gamma}} \chi(\kappa(i), \kappa(j)). \tag{5}
 \end{aligned}$$

Here Γ is a connected, simply-connected undirected graph with vertices I , $\kappa : I \rightarrow K(\mathcal{A})$ has $\sum_{i \in I} \kappa(i) = \alpha$, and $U(\Gamma, I, \kappa; \tau, \tilde{\tau})$ in \mathbb{Q} are explicit combinatorial coefficients.

3. A Lie algebra morphism

$$\tilde{\Psi} : SF^{\text{ind}}(\mathfrak{M}) \rightarrow \tilde{C}(X)$$

We can now explain our new work. We want to modify the Lie algebra morphism Ψ by inserting Behrend's microlocal function ν as a weight in its definition of Ψ , to get a new Lie algebra morphism $\tilde{\Psi}$. As ν is a 'multiplicity function', the new *generalized D–T invariants* $\bar{DT}^\alpha(\tau)$ we define using $\tilde{\Psi}$ will count sheaves with multiplicity, and so they will be unchanged under deformations of X .

Surprisingly, we also have to change the signs in the Lie algebra $C(X)$.

Define a Lie algebra $\tilde{C}(X)$ to have basis, as a \mathbb{Q} -vector space, symbols \tilde{c}^α for $\alpha \in K(\mathcal{A})$, and Lie bracket

$$[\tilde{c}^\alpha, \tilde{c}^\beta] = (-1)^{\chi(\alpha, \beta)} \chi(\alpha, \beta) \tilde{c}^{\alpha + \beta}, \quad (6)$$

which is (4) with an extra factor $(-1)^{\chi(\alpha, \beta)}$.

Define a linear map $\tilde{\Psi} : \text{SF}^{\text{ind}}(\mathfrak{M}) \rightarrow \tilde{C}(X)$ by $\tilde{\Psi}(f) = \sum_{\alpha \in K(\mathcal{A})} \bar{\chi}(f|_{\mathcal{M}_{\mathcal{A}}^{\alpha}}, \nu) \tilde{c}^{\alpha}$, where $\bar{\chi}(\cdot \cdot \cdot, \nu)$ is $\bar{\chi}$ weighted by ν .

Theorem. $\tilde{\Psi} : \text{SF}^{\text{ind}}(\mathfrak{M}) \rightarrow \tilde{C}(X)$ is a Lie algebra morphism.

This follows from my previous proof that Ψ is a Lie algebra morphism, together with two multiplicative identities for the Behrend function ν , that is

$$\nu(E_1 \oplus E_2) = (-1)^{\chi([E_1], [E_2])} \nu(E_1) \nu(E_2), \quad (7)$$

$$\int_{\epsilon \in P(\text{Ext}^1(E_2, E_1))} \nu(F) d\chi - \int_{\epsilon \in P(\text{Ext}^1(E_1, E_2))} \nu(F) d\chi = \quad (8)$$

$$(\dim \text{Ext}^1(E_2, E_1) - \dim \text{Ext}^1(E_1, E_2)) \nu(E_1 \oplus E_2),$$

where in the first integral in (8), F is defined in terms of ϵ such that the exact sequence $0 \rightarrow E_1 \rightarrow F \rightarrow E_2 \rightarrow 0$ corresponds to $\epsilon \in P(\text{Ext}^1(E_2, E_1))$, and similarly for the second integral.

4. Proving the Behrend function identities (7),(8)

Let \mathfrak{F} be a \mathbb{C} -scheme or Artin \mathbb{C} -stack, locally of finite type. The Behrend function $\nu_{\mathfrak{F}}$ is a \mathbb{Z} -valued constructible function on \mathfrak{F} which measures the ‘multiplicity’ of \mathfrak{F} at each point. In general it is difficult to compute. But there is a special case in which we can give an explicit formula for $\nu_{\mathfrak{F}}$: suppose \mathfrak{F} is a \mathbb{C} -scheme, U is a complex manifold, $f : U \rightarrow \mathbb{C}$ is holomorphic, and \mathfrak{F} is locally isomorphic (in the analytic topology) to $\text{Crit}(f)$ as a complex analytic space. Then

$$\nu_{\mathfrak{F}}(x) = (-1)^{\dim U} (1 - \chi(MF_f(x))),$$

with $MF_f(x)$ the *Milnor fibre* of f at x .

Our proof of (7),(8) involves first showing that we can write an atlas for the moduli stack \mathfrak{M} of coherent sheaves on a Calabi–Yau 3-fold X over \mathbb{C} in the form $\text{Crit}(f)$ locally in the analytic topology, for f a holomorphic function on a complex manifold U . Note that f, U are *not* algebraic, they are constructed by transcendental, gauge-theoretic methods. Our proof works only over \mathbb{C} , not for more general fields \mathbb{K} .

The proof has three steps:

(a) Show that the moduli stack \mathfrak{M} of coherent sheaves on X is locally isomorphic (in the Zariski topology) to the moduli stack \mathfrak{Vect} of vector bundles on X . (This works for Calabi–Yau m -folds X over \mathbb{K} for any m, \mathbb{K} .)

(b) Show that an atlas for \mathfrak{Vect} near $[E]$ can be locally written in the form $\text{Crit}(f)$ for $f : U \rightarrow \mathbb{C}$, where f, U are invariant under at least the maximal compact subgroup of $\text{Aut}(E)$.

(c) Prove (7),(8) using an atlas near $E = E_1 \oplus E_2$, and localizing under the action of the $U(1)$ group $\{\text{id}_{E_1} + \lambda \text{id}_{E_2} : \lambda \in U(1)\}$.

For (a), one uses Seidel–Thomas twists to show the local equivalence of moduli of sheaves and vector bundles. Given an integer n , the Seidel–Thomas twist with $\mathcal{O}_X(-n)$, T_n , is the Fourier–Mukai transform from $D(X)$ to $D(X)$ with kernel:

$$\text{cone}(\mathcal{O}_X(n) \boxtimes \mathcal{O}_X(-n) \rightarrow \mathcal{O}_\Delta).$$

Given $E \in \mathfrak{M}$. For $n \gg 0$, $F = T_n(E)$ is a *sheaf*, not a more general complex, and we have:

$$0 \rightarrow F \rightarrow \mathcal{O}_X(-n) \otimes H^0(E(n)) \rightarrow E \rightarrow 0.$$

As X is Calabi–Yau, T_n induces local isomorphisms of moduli spaces. We inductively define integers $n_1, \dots, n_m \gg 0$ and set $F_i = T_{n_i} \circ T_{n_{i-1}} \dots \circ T_{n_1}(E)$. We get an exact sequence:

$$\begin{aligned} 0 \rightarrow & F_m \rightarrow \mathcal{O}_X(-n_m) \otimes H^0(F_{m-1}(m)) \rightarrow \\ \dots \rightarrow & \mathcal{O}_X(-n_1) \otimes H^0(E(n_1)) \rightarrow E \rightarrow 0. \end{aligned}$$

By the Hilbert Syzygy Theorem, F_m is a vector bundle.

For (b), we use an idea of Richard Thomas. Let $E \rightarrow X$ be a fixed complex (not holomorphic) vector bundle. The holomorphic structures on E are $\bar{\partial}$ -operators $\bar{\partial}_E : C^\infty(E) \rightarrow C^\infty(E \otimes_{\mathbb{C}} \Lambda^{0,1} T^* X)$. The set of such $\bar{\partial}$ -operators is an infinite-dimensional affine space \mathcal{A} . A $\bar{\partial}$ -operator $\bar{\partial}_E$ is a holomorphic structure iff the $(0, 2)$ -curvature $\bar{\partial}_E^2$ is zero. Gauge transformations $\mathcal{G} = C^\infty(\text{Aut}(E))$ act on \mathcal{A} . Thus, the moduli space (stack) of holomorphic structures on E up to isomorphisms is

$$\mathcal{M}_E = \{\bar{\partial}_E \in \mathcal{A} : \bar{\partial}_E^2 = 0\} / \mathcal{G}.$$

Richard observed that $\{\bar{\partial}_E \in \mathcal{A} : \bar{\partial}_E^2 = 0\}$ is $\text{Crit}(CS)$, in some infinite-dimensional manifold sense, where $CS : \mathcal{A} \rightarrow \mathbb{C}$ is the *holomorphic Chern–Simons functional*.

To prove (b), we show that an atlas for \mathfrak{Vect} near $(E, \bar{\partial}_E)$ can be written locally as $\text{Crit}(CS|_U)$, where U is a finite-dimensional complex submanifold of \mathcal{A} , which is roughly speaking transverse to the orbit of \mathcal{G} through $\bar{\partial}_E$. We use results of Miyajima and others which locally identify the moduli spaces of holomorphic structures on E , and of analytic vector bundles on X , and of algebraic vector bundles on X .

To prove (c): let $E = E_1 \oplus E_2$ be a coherent sheaf on X . Then (a),(b) show that we can write an atlas for \mathfrak{M} near E as $\text{Crit}(f)$ near 0, where f is a holomorphic function defined near 0 on $\text{Ext}^1(E_1 \oplus E_2, E_1 \oplus E_2)$, and f is invariant under the action of $T = \{\text{id}_{E_1} + \lambda \text{id}_{E_2} : \lambda \in U(1)\}$ on $\text{Ext}^1(E_1 \oplus E_2, E_1 \oplus E_2)$ by conjugation. The fixed points of T on $\text{Ext}^1(E_1 \oplus E_2, E_1 \oplus E_2)$ are $\text{Ext}^1(E_1, E_1) \oplus \text{Ext}^1(E_2, E_2)$, and that the restriction of f to these fixed points is $f_1 + f_2$, where f_j is defined near 0 in $\text{Ext}^1(E_j, E_j)$, and $\text{Crit}(f_j)$ is an atlas for \mathfrak{M} near E_j .

The Milnor fibre $MF_f(0)$ is invariant under T , so by localization we have

$$\chi(MF_f(0)) = \chi(MF_f(0)^T) = \chi(MF_{f_1+f_2}(0)).$$

The Thom–Sebastiani theorem gives

$$1 - \chi(MF_{f_1+f_2}(0)) = (1 - \chi(MF_{f_1}(0))) \\ (1 - \chi(MF_{f_2}(0))).$$

Equation (7) then follows easily from

$$\nu_{\mathfrak{M}}(E) = (-1)^{\dim \text{Ext}^1(E,E) - \dim \text{Hom}(E,E)} \\ (1 - \chi(MF_f(0))),$$

and the analogues for E_1, E_2 . Equation (8) uses a more involved argument to do with Milnor fibres of f at non-fixed points of the $U(1)$ -action.

5. Generalized D–T invariants

We then define invariants $\bar{D}T^\alpha(\tau) \in \mathbb{Q}$ by $\tilde{\Psi}(\bar{\epsilon}^\alpha(\tau)) = \bar{D}T^\alpha(\tau)\tilde{c}^\alpha$ for all $\alpha \in K(\mathcal{A})$. Since $\tilde{\Psi}$ is a Lie algebra morphism, and the $\bar{\epsilon}^\alpha(\tau)$ satisfy a universal transformation law under change of stability condition, it follows that the $\bar{D}T^\alpha(\tau)$ satisfy a known transformation law under change of stability condition. When $\mathcal{M}_{\text{st}}^\alpha(\tau) = \mathcal{M}_{\text{ss}}^\alpha(\tau)$ we have $\bar{\epsilon}^\alpha(\tau) = \bar{\delta}_{\text{ss}}^\alpha(\tau)$, giving

$$\bar{D}T^\alpha(\tau) = \int_{\mathcal{M}_{\text{st}}^\alpha(\tau)} \nu \, d\chi = DT^\alpha(\tau) \quad (9)$$

by (2). Thus, the $\bar{D}T^\alpha(\tau)$ are generalizations of Donaldson–Thomas invariants. It remains to show that the $\bar{D}T^\alpha(\tau)$ are unchanged under deformations of the underlying Calabi–Yau 3-fold X .

To do this we define an auxiliary invariant $PI^\alpha(N, \tau) \in \mathbb{Z}$ counting ‘stable pairs’ (E, s) with E a semistable sheaf in class α and $s \in H^0(E \otimes \mathcal{L}^N)$, for $N \gg 0$, where \mathcal{L} is the ample line bundle used to define τ . By a similar proof to Pandharipande–Thomas invariants, the moduli space of stable pairs has a symmetric obstruction theory, so $PI^\alpha(N, \tau)$ is unchanged by deformations of X .

We then prove that $PI^\alpha(N, \tau)$ can be written in terms of the $\bar{DT}^\beta(\tau)$ by

$$PI^\alpha(N, \tau) = \sum_{\substack{\alpha_1, \dots, \alpha_n \in K(\mathcal{A}): \\ \alpha_1 + \dots + \alpha_n = \alpha, \\ \tau(\alpha_i) = \tau(\alpha) \forall i}} \frac{(-1)^n}{n!} \prod_{i=1}^n (-1)^{\chi([\mathcal{L}^{-N}] - \alpha_1 - \dots - \alpha_{i-1}, \alpha_i)} \chi([\mathcal{L}^{-N}] - \alpha_1 - \dots - \alpha_{i-1}, \alpha_i) \bar{DT}^{\alpha_i}(\tau). \quad (10)$$

We prove (10) using a change of stability condition formula in an auxiliary abelian category \mathcal{B} , whose objects are triples (V, E, ϕ) for V a finite-dimensional \mathbb{C} -vector space, E a coherent sheaf, and $\phi : V \rightarrow H^0(E \otimes \mathcal{L}^N)$ a linear map. Now (10) implies that

$$PI^\alpha(N, \tau) = (-1)^{\chi([\mathcal{L}^{-N}], \alpha)} \chi([\mathcal{L}^{-N}], \alpha) \bar{DT}^\alpha(\tau) + \dots,$$

where the lower order terms ‘ \dots ’ involve only $\bar{DT}^\beta(\tau)$ with $\dim \beta = \dim \alpha$ and $\text{rank } \beta < \text{rank } \alpha$.

Also $\chi([\mathcal{L}^{-N}], \alpha) = \dim H^0(E \otimes \mathcal{L}^N) > 0$ for $N \gg 0$. Thus, fixing $\dim \alpha$ and arguing by induction on $\text{rank } \alpha$, since $PI^\alpha(N, \tau)$ is deformation-invariant, we see that $\bar{DT}^\alpha(\tau)$ is deformation-invariant.

Integrality properties of the invariants

Suppose E is stable and rigid in class α . Then $kE = E \oplus \cdots \oplus E$ is strictly semistable in class $k\alpha$, for $k \geq 2$. Calculations show that E contributes 1 to $\bar{D}T^\alpha(\tau)$, and kE contributes $1/k^2$ to $\bar{D}T^{k\alpha}(\tau)$. So we do not expect the $\bar{D}T^\alpha(\tau)$ to be integers, in general.

Define new invariants $KS^\alpha(\tau) \in \mathbb{Q}$ by

$$\bar{D}T^\alpha(\tau) = \sum_{k \geq 1: k \text{ divides } \alpha} \frac{1}{k^2} KS^{\alpha/k}(\tau).$$

Then the kE for $k \geq 1$ above contribute 1 to $KS^\alpha(\tau)$ and 0 to $KS^{k\alpha}(\tau)$ for $k > 1$.

Conjecture. *Suppose τ is generic, in the sense that $\tau(\alpha) = \tau(\beta)$ implies $\chi(\alpha, \beta) = 0$. Then $KS^\alpha(\tau) \in \mathbb{Z}$ for all $\alpha \in K(\mathcal{A})$.*

These $KS^\alpha(\tau)$ may coincide with invariants conjectured by Kontsevich–Soibelman, and in String Theory should perhaps be interpreted as ‘numbers of BPS states’.